

# Uniform bounds for robust mean estimators

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ITA Workshop, Robust Learning

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- Presence of **outliers** of unknown nature:
  - ⇒ requires algorithms that are **robust**.
- We would like to develop **general methods** that work under **minimal assumptions**.
- A natural way to model “noisy” data is via **heavy-tailed distributions**.
- For the purpose of this talk, a random variable  $X$  has heavy-tailed distribution if

$$\mathbb{E}|X|^r = \infty$$

for some  $r > 0$  (for example,  $r = 2.1$ ).

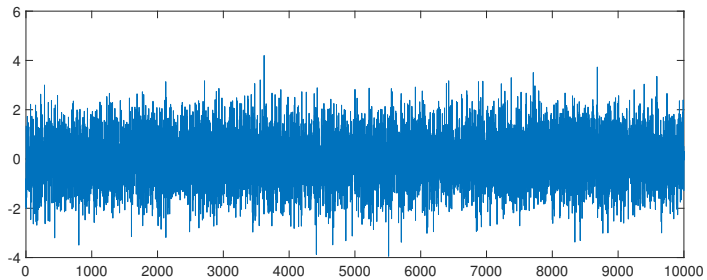


Figure: Standard normal distribution.

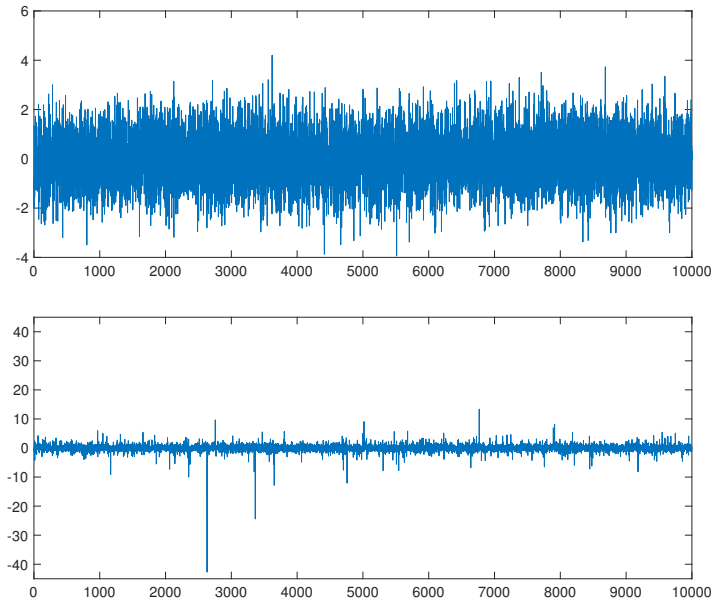


Figure: Student's t-distribution with 3 d.f.

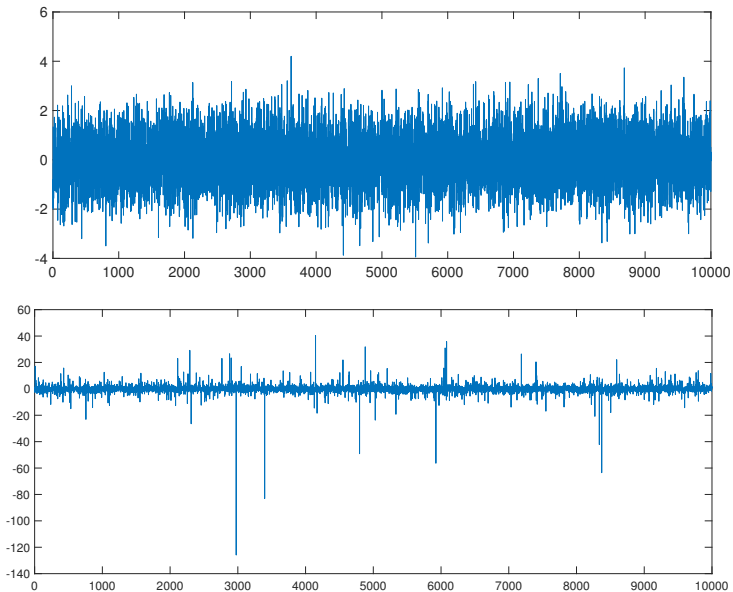


Figure: Student's t-distribution with 2.1 d.f.

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- Benchmark: assume that  $X_1, \dots, X_N$  are i.i.d.  $\mathcal{N}(\mu, \sigma^2)$ .
- The sample mean  $\hat{\mu}_N := \frac{1}{N} \sum_{j=1}^N X_j$  satisfies

$$\Pr \left( |\hat{\mu}_N - \mu| \geq \sigma \sqrt{\frac{2 \log(1/\alpha)}{N}} \right) \leq 2\alpha,$$

similar inequality holds for sub-Gaussian distributions.

## Question: how to estimate the mean?

- What if  $X_1, \dots, X_N$  are i.i.d. copies of  $X \sim \Pi$  such that

$$\mathbb{E}X = \mu, \text{ Var}(X) \leq \sigma^2?$$

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- Guarantees for the sample mean  $\hat{\mu}_n = \frac{1}{N} \sum_{j=1}^N X_j$  are not completely satisfactory:

$$\Pr \left( |\hat{\mu}_N - \mu| \geq \sigma \sqrt{\frac{(1/\alpha)}{N}} \right) \leq \alpha.$$

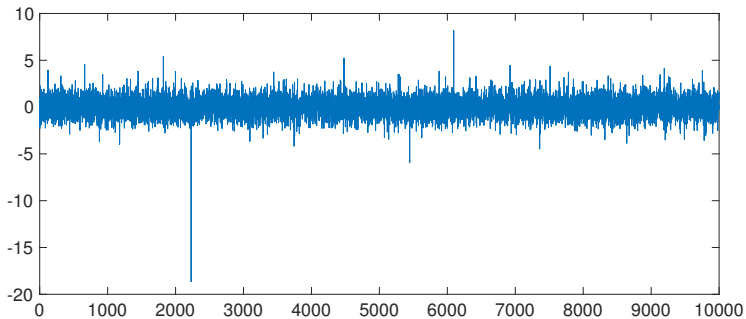


Figure: Rescaled Sample Means of Student's t-distribution with **3 d.f.**

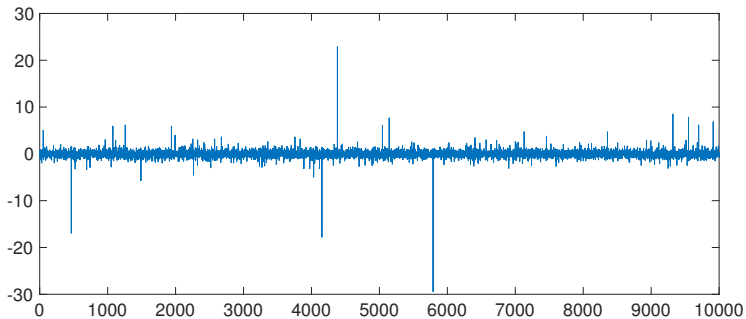


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- **Median-of-means (MOM) estimator:** [A. Nemirovski, D. Yudin '83; N. Alon, Y. Matias, M. Szegedy '96; R. Oliveira, M. Lerasle '11]

Split the sample into  $k = \lfloor \log(1/\alpha) \rfloor + 1$  groups  $G_1, \dots, G_k$  of size  $\simeq N/k$  each:

$$\underbrace{\overbrace{X_1, \dots, X_{|G_1|}}^{G_1} \dots \overbrace{X_{N-|G_k|+1}, \dots, X_N}^{G_k}}_{\hat{\mu}^{(k)} := \text{median}(\bar{\mu}_1, \dots, \bar{\mu}_k)}$$

$\bar{\mu}_1 := \frac{1}{|G_1|} \sum_{x_j \in G_1} x_j$        $\bar{\mu}_k := \frac{1}{|G_k|} \sum_{x_j \in G_k} x_j$

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- Claim:

$$\Pr \left( |\hat{\mu}^{(k)} - \mu| \geq 6.4 \sigma \sqrt{\frac{\log(1/\alpha)}{N}} \right) \leq \alpha$$

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- Has recently been extended to multivariate mean and covariance estimation, empirical risk minimization, U-statistics.

**Quickly growing body of work:** G. Chinot, L. Devroye, E. Joly, G. Lecué, M. Lerasle, G. Lugosi, T. Matthieu, S. Mendelson, R. Oliveira, S. Hopkins, N. Zhivotovsky.

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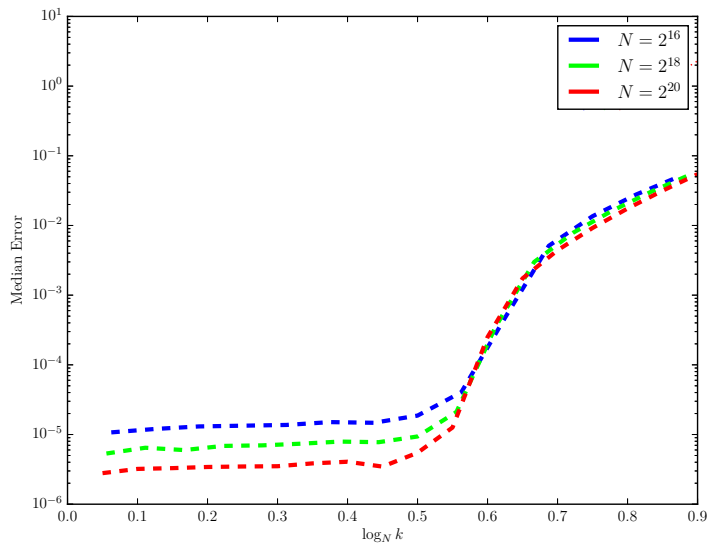
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- Similar results were obtained by J. Fan, W.-X. Zhou, Z. Ren, O. Catoni, I. Giulini using different estimation techniques.

## Performance as $k$ changes



Result so far:

$$\Pr \left( |\hat{\mu}^{(k)} - \mu| \geq C \sigma \sqrt{\frac{k}{N}} \right) \leq e^{-k} := \alpha$$

- Need to recalculate the estimator for different values of confidence parameter  $\alpha$ . Can one "decouple"  $k$  and  $\alpha$ ?

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- Assume that many means need to be estimated **simultaneously**. Uniform deviation bounds?
- Robust estimator that does not depend on the random partition of the index set?
- Algorithms for robust Empirical Risk Minimization?

# Connections between symmetry and robustness

- 1 If the distribution  $P$  is symmetric, then its center of symmetry  $\theta(P)$  can be approximated by a robust estimator with a high breakdown point, e.g. a robust M-estimator

$$\hat{\theta} := \operatorname{argmin}_{z \in \mathbb{R}} \sum_{j=1}^N \rho(z - X_j) .$$

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- ② In order to obtain a robust estimator of a parameter  $\theta(P)$  of (not necessarily symmetric) distribution  $P$  based on the i.i.d. sample  $X_1, \dots, X_N$ , create a new sample such that
- (i) it is governed by an approximately symmetric distribution;
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How does one create such a "new sample"? A possible approach is based on the fact that  
as sample size grows, the summary statistics of the data become asymptotically normal,  
hence asymptotically symmetric. Examples: sample mean, MLE.

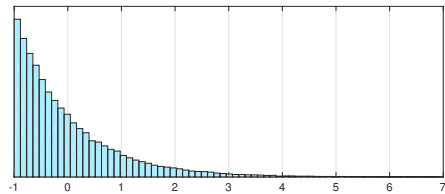


Figure: Centered exponential distribution

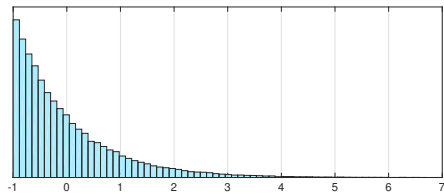


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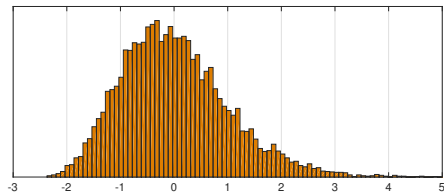


Figure: Rescaled sample means with  $n = 10$ .

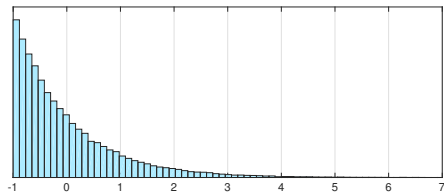


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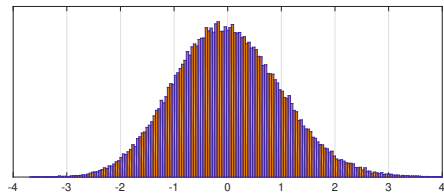


Figure: Rescaled sample means with  $n = 100$ .

# Robust estimators of the mean

- Split the sample into  $k$  groups  $G_1, \dots, G_k$  of size  $n_j = |G_j|$  each:

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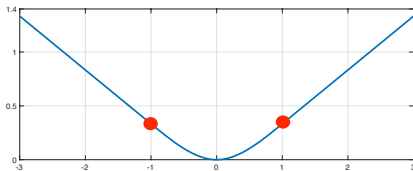
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- Examples:
  - $\rho(x) = |x|$  yields the median-of-means estimator.
  - $\rho(x) = \text{Huber's loss}$ :



# Non-asymptotic guarantees

- $X_1, \dots, X_N$  are i.i.d., with mean  $\mu$  and variance  $\sigma^2$ .
- Will assume that  $n_1 = \dots = n_k = n$  during the talk.
- $\Phi(t)$  - distribution function of  $N(0, 1)$ , and

$$g(n) := \sup_{t \in \mathbb{R}} \left| \mathbb{P} \left( \sqrt{n} \frac{\bar{X}_n - \mathbb{E}X}{\sqrt{\text{Var}(X)}} \leq t \right) - \Phi(t) \right|.$$

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## Theorem (M., 2018)

For all  $s > 0$  such that  $\sqrt{\frac{s}{k}} + g(n) \leq \underline{c}(\rho)$ ,

$$\left| \hat{\mu}^{(k)} - \mu \right| \leq \bar{C}(\rho) \tilde{\Delta} \left( \sqrt{\frac{s}{N}} + g(n) \sqrt{\frac{k}{N}} \right)$$

with probability at least  $1 - 2e^{-s}$ .

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- Moreover, if  $k \leq C/g^2(n)$ , then  $\mathbb{E} \left| \hat{\mu}^{(k)} - \mu \right| \leq C(\rho) \frac{\tilde{\Delta}}{\sqrt{N}}$ .

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Add  $\mathcal{O}$  arbitrary (e.g., adversarially generated) outliers:

## Theorem (M., 2018)

For all  $\mathcal{O} \in \mathbb{N}$ ,  $s > 0$  such that  $\sqrt{\frac{s}{k}} + g(n) + \frac{\mathcal{O}}{k} \leq \underline{c}(\rho) \left(1 - \frac{\mathcal{O}}{k}\right)$ ,

$$\left| \hat{\mu}^{(k)} - \mu \right| \leq \bar{C}(\rho) \tilde{\Delta} \left( \sqrt{\frac{s}{N}} + g(n) \sqrt{\frac{k}{N}} + \frac{\mathcal{O}}{\sqrt{k}} \frac{1}{\sqrt{N}} \right)$$

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- If  $\mathcal{O} = \varepsilon \cdot N$ , then “optimal”  $k \simeq \varepsilon^{2/3} N$  and resulting error is of order  $\varepsilon^{2/3}$ .

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- $\rho(x) = |x| \implies \Delta^2 = \frac{\pi}{2}$ .
- $\rho(x) = \begin{cases} z^2/2, & |z| \leq M, \\ M|z| - M^2/2, & |z| > M \end{cases} \implies \Delta^2 = \frac{\int_{-M}^M x^2 d\Phi(x) + 2M^2(1 - \Phi(M))}{(2\Phi(M) - 1)^2}$ .

For instance,  $\Delta^2 \simeq 1.15$  for  $M = 2$  and  $\Delta^2 \simeq 1.01$  for  $M = 3$ .

# Uniform deviation bounds

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- $g(f; n) := \sup_{t \in \mathbb{R}} \left| \mathbb{P} \left( \sqrt{n} \frac{\bar{\mu}_j(f) - \mathbb{E}f(X)}{\sqrt{\text{Var}(f(X))}} \leq t \right) - \Phi(t) \right|.$

# Uniform deviation bounds

$$\sigma^2(\mathcal{F}) = \sup_{f \in \mathcal{F}} \text{Var}(f(X)), \quad \tilde{\Delta} = \max(\Delta, \sigma(\mathcal{F}))$$

## Theorem (M., 2018/19)

Assume that  $\rho'$  is Lipschitz continuous. Then for all  $s > 0$  such that

$$\max \left( \frac{1}{\sqrt{k} \Delta} \mathbb{E} \sup_{f \in \mathcal{F}} \left| \frac{1}{\sqrt{N}} \sum_{j=1}^N (f(X_j) - \mathbb{E}f(X)) \right|, \sqrt{\frac{s}{k}} + \sup_{f \in \mathcal{F}} g(f; n) \right) \leq \underline{c}(\rho),$$

the inequality

$$\begin{aligned} \sup_{f \in \mathcal{F}} \left| \hat{\mu}^{(k)}(f) - \mathbb{E}f(X) \right| &\leq \bar{C}(\rho) \left( \frac{1}{\sqrt{N} \Delta} \tilde{\Delta} \mathbb{E} \sup_{f \in \mathcal{F}} \left| \frac{1}{\sqrt{N}} \sum_{j=1}^N (f(X_j) - \mathbb{E}f(X)) \right| \right. \\ &\quad \left. + \tilde{\Delta} \left( \sqrt{\frac{s}{N}} + \sup_{f \in \mathcal{F}} g(f; n) \sqrt{\frac{k}{N}} \right) \right) \end{aligned}$$

holds with probability  $\geq 1 - 2e^{-s}$ .

## Estimators of the mean of a random vector

- $X_1, \dots, X_N$  – i.i.d. copies of a random vector  $X \in \mathbb{R}^d$  with mean  $\mathbb{E}X = \mu$  and covariance matrix  $\mathbb{E}(X - \mu)(X - \mu)^T = \Sigma$ .

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- Can be used to construct the estimator  $\hat{\mu}^{(k)}$  that satisfies “sub-Gaussian” bound

$$\|\hat{\mu}^{(k)} - \mu\|_2 \leq \bar{C}(\rho) \left( \sqrt{\frac{\text{tr} \Sigma}{N}} + \sqrt{\lambda_{\max}(\Sigma)} \left( \sqrt{\frac{s}{N}} + \underbrace{\sup_{v: \|v\|_2=1} g(f_v; n)}_{\text{“bias” of smaller order}} \sqrt{\frac{k}{N}} \right) \right)$$

with probability  $\geq 1 - 2e^{-s}$ , as long as  $k \gtrsim \frac{\text{tr} \Sigma}{\lambda_{\max}(\Sigma)}$  and  $s \lesssim k$ .

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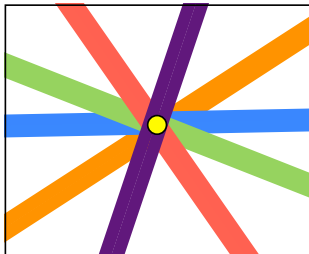
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- Finally, let  $\varepsilon_* := \inf \{\varepsilon > 0 : M(\varepsilon) \neq \emptyset\}$ , and take  $\hat{\mu}^{(k)}$  to be any element in  $M(\varepsilon_*)$ .

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- Does not depend on random partition and satisfies the same deviation guarantees as  $\hat{\mu}^{(k)}$ .

Thank you for listening!