#### **Robust Sparse Statistics**

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#### Overview

- Sparse Estimation
- Robust Version
- Convex Relaxation
- Further Directions

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### Sparse Mean Estimation

- Given  $X \sim N(\mu, I) \subset \mathbb{R}^d$  it takes  $O(d/\epsilon^2)$  samples to learn  $\mu$  to error  $\epsilon$ .
- What if extra information is known about  $\mu$ ? Can we do better?
  - In particular, what if  $\mu$  is known to be sparse?

## Sparse Mean Estimation

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  - In particular, what if  $\mu$  is known to be sparse?

If  $|\mu|_0 \leq k$ , then with  $O(k \log(d)/\epsilon^2)$  samples suffices:

- Sample mean learns each coordinate to error  $\epsilon/2\sqrt{k}$ .
- Truncating to k largest coordinates  $(\hat{\mu}_k)$  gives error  $\epsilon$ .
- For  $k \ll d$ , this is a substantial improvement.

# Robust Sparse Mean Estimation

What if we want to do this robustly? Can we learn  $\mu$  up to error  $\tilde{O}(\epsilon)$  in the presence of adversarial errors with o(d) samples?

# Robust Sparse Mean Estimation

- What if we want to do this robustly? Can we learn  $\mu$  up to error  $O(\epsilon)$  in the presence of adversarial errors with o(d) samples?
- First considered by [Balakrishnan-Du-Li-Singh '17].

Non-Sparse Robust Mean Estimation:

- $\hat{\mu} ~\approx \mu$  unless there is a  $|v|_2 = 1$  with  $v \cdot (\hat{\mu} \mu)$  large.
- If such v exists,  $Var(v \cdot X)$  large.
- Determine if there is a v with  $|v|_2 = 1$  and  $v^T \text{Cov}(X)v$  large.
  - If not, return  $\hat{\mu}$
  - If so, filter on  $v \cdot X$  and repeat

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Sparse Robust Mean Estimation:

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Sparse Robust Mean Estimation:

- $\hat{\mu}_{k} \approx \mu$  unless there is a  $|v|_{2} = 1$  with  $v \cdot (\hat{\mu} \mu)$  large.
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Sparse Robust Mean Estimation:

- $\hat{\mu}_{k} \approx \mu$  unless there is a 2*k*-sparse  $|v|_{2} = 1$  with  $v \cdot (\hat{\mu} \mu)$  large.
- If such v exists,  $Var(v \cdot X)$  large.
- Determine if there is a v with  $|v|_2 = 1$  and  $v^T \text{Cov}(X)v$  large.
  - If not, return  $\hat{\mu}$
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# Sample Complexity

We need our good set of points to have:

- $v \cdot (\hat{\mu} \mu)$  small for  $v \ 2k$ -sparse.
- $Var(v \cdot X) \approx 1$  for  $v \ 2k$ -sparse.
- $v \cdot X$  to have appropriate tails for  $v \ 2k$ -sparse.

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Can cover 2k-sparse vectors with cover of size  $\binom{d}{2k} 2^{O(k)}$ . Need  $O(k \log(d)/\epsilon^2)$  samples.

#### Problem

To find directions of large variance need to solve:

 $\sup_{|v|_2 \le 1, |v|_0 \le 2k} v^T M v$ 

with  $M = \operatorname{Cov}(X)$ .

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This is NP-Hard in general!

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#### Convex Relaxation

Instead solve a relaxation.

- If v is 2k-sparse,  $|v|_1 \leq \sqrt{2k}$ .
- $|vv^{T}|_{1} \leq 2k$  and  $vv^{T} \cdot Cov(X)$  large.

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#### Convex Relaxation

Instead solve a relaxation.

$$\sup_{H \ge 0, |H|_1 \le 2k, \operatorname{tr}(H) = 1} H \cdot \operatorname{Cov}(X).$$
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#### Convex Relaxation

Instead solve a relaxation.

• If 
$$v$$
 is  $2k$ -sparse,  $|v|_1 \le \sqrt{2k}$ .  
•  $|vv^T|_1 \le 2k$  and  $vv^T \cdot \operatorname{Cov}(X)$  large.  
Solve  
 $\sup H \cdot \operatorname{Cov}(X)$ . (1)

$$\sup_{\substack{H \ge 0, |H|_1 \le 2k, \operatorname{tr}(H) = 1}} H \cdot \operatorname{Cov}(X).$$

- If solution is small,  $\hat{\mu}_k \approx \mu$ .
- If not, filter?

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### **Good Samples**

Assuming that we took  $\Omega(k^2 \log(d)/\epsilon^2)$  samples, with high probability each entry of  $\hat{\Sigma} - \Sigma$  is  $O(\epsilon/k)$ .

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If so, for any H with  $|H|_1 \leq 2k$ , and  $\operatorname{tr}(H) = 1$ 

$$H\cdot\hat{\Sigma}=H\cdot\Sigma+O(\epsilon)=1+O(\epsilon).$$

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If so, for any H with  $|H|_1 \leq 2k$ , and  $\operatorname{tr}(H) = 1$ 

$$H \cdot \hat{\Sigma} = H \cdot \Sigma + O(\epsilon) = 1 + O(\epsilon).$$

- If  $H \cdot \hat{\Sigma}$  is much larger, discrepancy due to bad samples.
- Filter entries where  $(x \hat{\mu})H(x \hat{\mu})$  is large (or add to convex program).

#### Upshot

Have an algorithm where if  $\mu$  is known to be k-sparse, learn  $\mu$  to error  $\tilde{O}(\epsilon)$  with  $\epsilon$  adversarial error with  $O(k^2 \log(d)/\epsilon^2)$  samples in polynomial time.

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#### Further Extensions

[BDLS] Also give robust sparse estimation algorithms for:

- Estimating  $\Sigma = I + \Omega$  when  $|\Omega|_0 \leq k$ .
- Estimating  $\Sigma = I + \rho v v^T$  when v is k-sparse.
- Linear regressions  $y \approx x \cdot \beta$  when  $\beta$  is *k*-sparse.

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Recent work by [Diakonikolas–Kane–Karmalkar–Price] does much of this using spectral techniques instead of convex programs.